

16 Basic timers (TIM6&TIM7)

Low-density value line devices are STM32F100xx microcontrollers where the Flash memory density ranges between 16 and 32 Kbytes.

Medium-density value line devices are STM32F100xx microcontrollers where the Flash memory density ranges between 64 and 128 Kbytes.

High-density value line devices are STM32F100xx microcontrollers where the Flash memory density ranges between 256 and 512 Kbytes.

This section applies to the whole STM32F100xx family, unless otherwise specified.

16.1 TIM6&TIM7 introduction

The basic timers TIM6 and TIM7 consist of a 16-bit auto-reload counter driven by a programmable prescaler.

They may be used as generic timers for time-base generation but they are also specifically used to drive the digital-to-analog converter (DAC). In fact, the timers are internally connected to the DAC and are able to drive it through their trigger outputs.

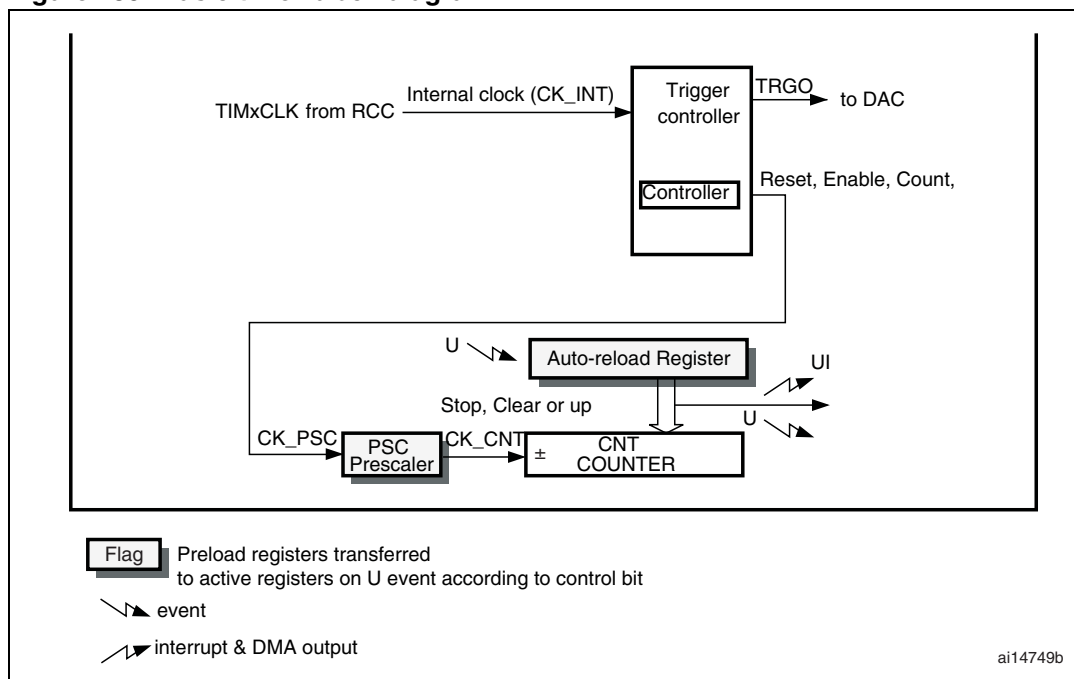
The timers are completely independent, and do not share any resources.

16.2 TIM6&TIM7 main features

Basic timer (TIM6&TIM7) features include:

- 16-bit auto-reload upcounter
- 16-bit programmable prescaler used to divide (also “on the fly”) the counter clock frequency by any factor between 1 and 65535
- Synchronization circuit to trigger the DAC
- Interrupt/DMA generation on the update event: counter overflow

Figure 186. Basic timer block diagram



16.3 TIM6&TIM7 functional description

16.3.1 Time-base unit

The main block of the programmable timer is a 16-bit upcounter with its related auto-reload register. The counter clock can be divided by a prescaler.

The counter, the auto-reload register and the prescaler register can be written or read by software. This is true even when the counter is running.

The time-base unit includes:

- Counter Register (TIMx_CNT)
- Prescaler Register (TIMx_PSC)
- Auto-Reload Register (TIMx_ARR)

The auto-reload register is preloaded. The preload register is accessed each time an attempt is made to write or read the auto-reload register. The contents of the preload register are transferred into the shadow register permanently or at each update event UEV, depending on the auto-reload preload enable bit (ARPE) in the TIMx_CR1 register. The update event is sent when the counter reaches the overflow value and if the UDIS bit equals 0 in the TIMx_CR1 register. It can also be generated by software. The generation of the update event is described in detail for each configuration.

The counter is clocked by the prescaler output CK_CNT, which is enabled only when the counter enable bit (CEN) in the TIMx_CR1 register is set.

Note that the actual counter enable signal CNT_EN is set 1 clock cycle after CEN.

Prescaler description

The prescaler can divide the counter clock frequency by any factor between 1 and 65536. It is based on a 16-bit counter controlled through a 16-bit register (in the TIMx_PSC register). It can be changed on the fly as the TIMx_PSC control register is buffered. The new prescaler ratio is taken into account at the next update event.

Figure 187 and Figure 188 give some examples of the counter behavior when the prescaler ratio is changed on the fly.

Figure 187. Counter timing diagram with prescaler division change from 1 to 2

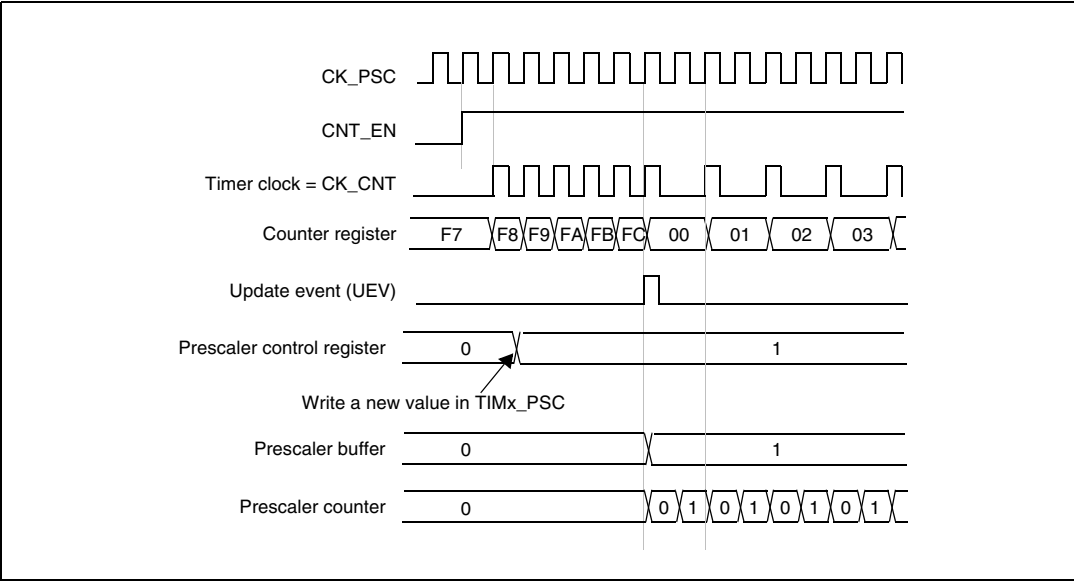
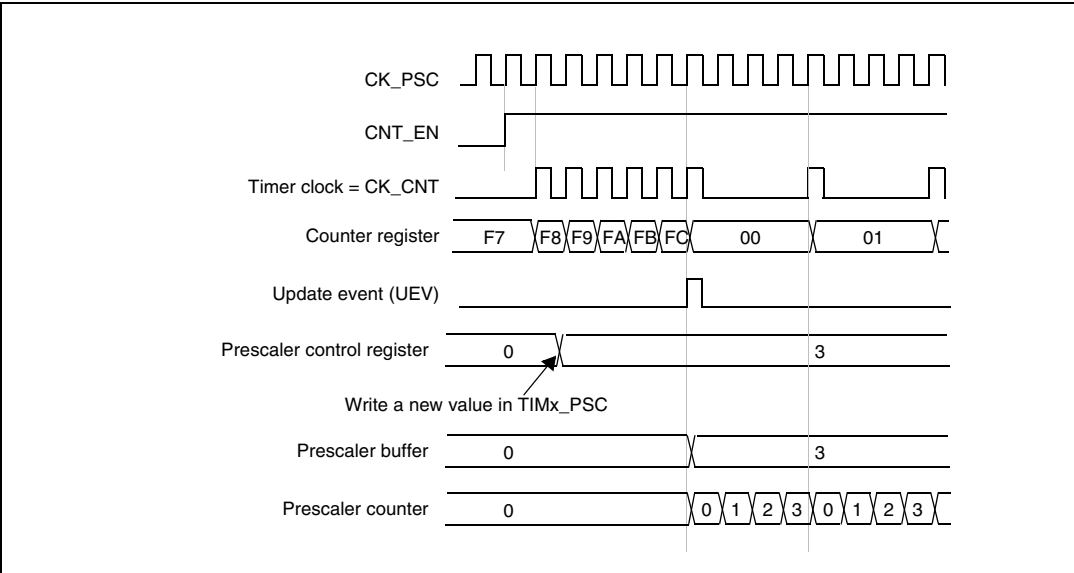


Figure 188. Counter timing diagram with prescaler division change from 1 to 4



16.3.2 Counting mode

The counter counts from 0 to the auto-reload value (contents of the TIMx_ARR register), then restarts from 0 and generates a counter overflow event.

An update event can be generated at each counter overflow or by setting the UG bit in the TIMx_EGR register (by software or by using the slave mode controller).

The UEV event can be disabled by software by setting the UDIS bit in the TIMx_CR1 register. This avoids updating the shadow registers while writing new values into the preload registers. In this way, no update event occurs until the UDIS bit has been written to 0, however, the counter and the prescaler counter both restart from 0 (but the prescale rate does not change). In addition, if the URS (update request selection) bit in the TIMx_CR1 register is set, setting the UG bit generates an update event UEV, but the UIF flag is not set (so no interrupt or DMA request is sent).

When an update event occurs, all the registers are updated and the update flag (UIF bit in the TIMx_SR register) is set (depending on the URS bit):

- The buffer of the prescaler is reloaded with the preload value (contents of the TIMx_PSC register)
- The auto-reload shadow register is updated with the preload value (TIMx_ARR)

The following figures show some examples of the counter behavior for different clock frequencies when TIMx_ARR = 0x36.

Figure 189. Counter timing diagram, internal clock divided by 1

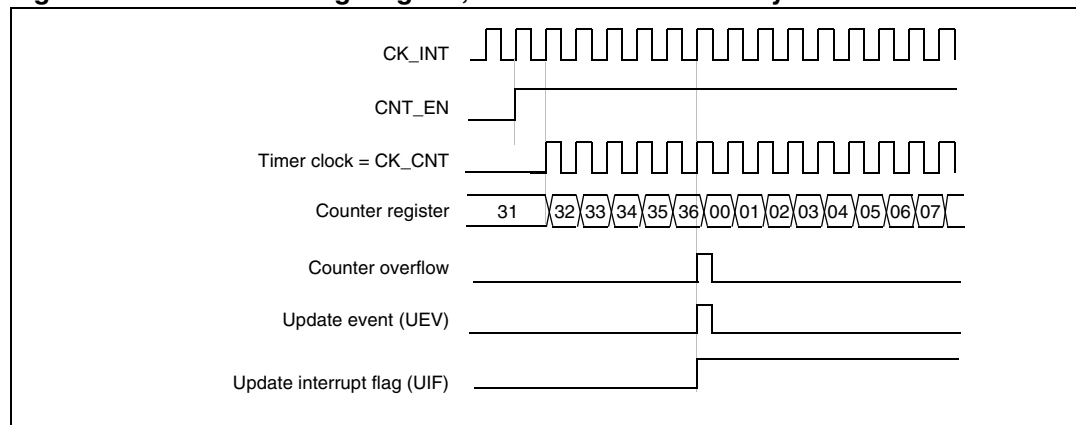


Figure 190. Counter timing diagram, internal clock divided by 2

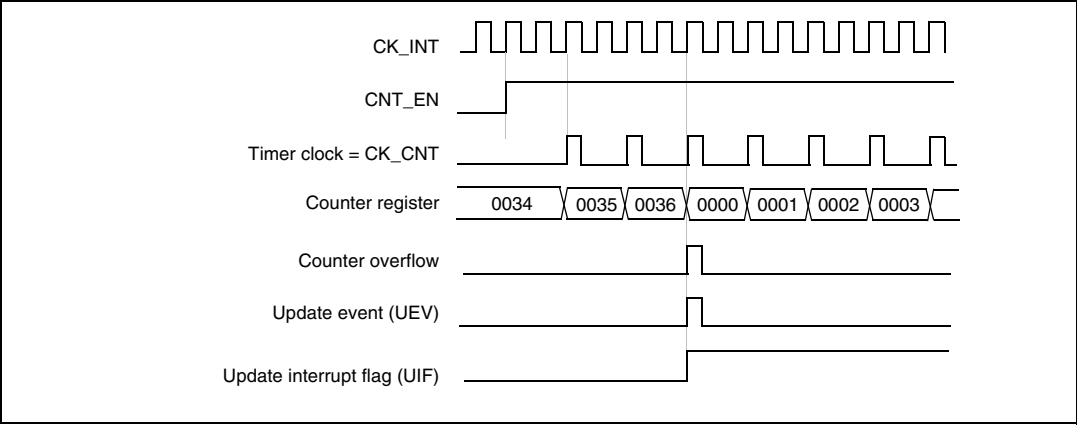


Figure 191. Counter timing diagram, internal clock divided by 4

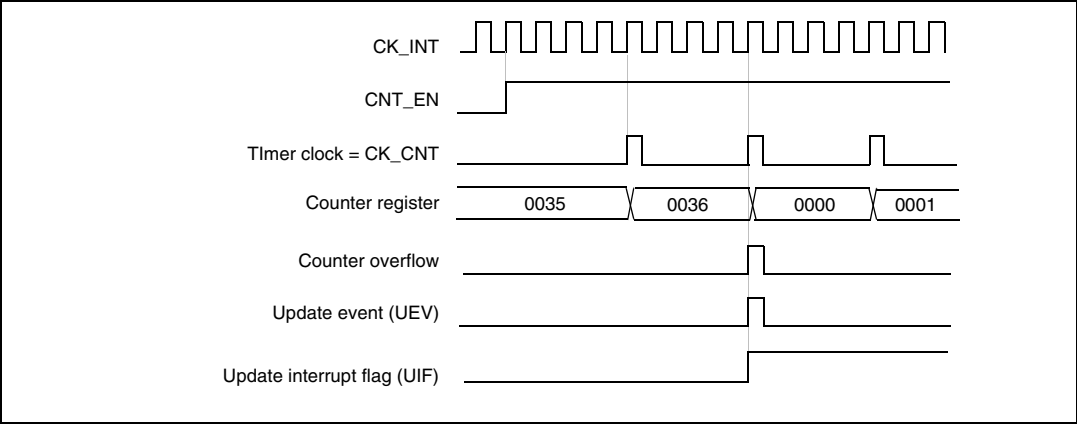


Figure 192. Counter timing diagram, internal clock divided by N

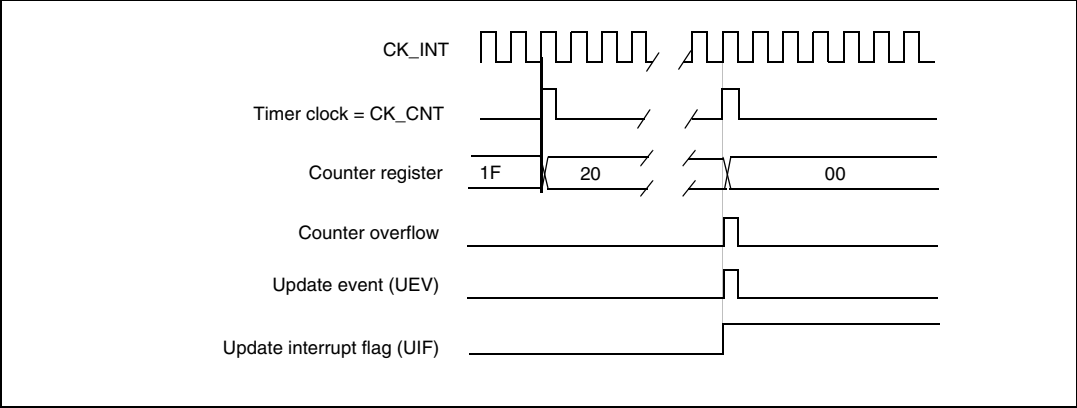


Figure 193. Counter timing diagram, update event when ARPE = 0 (TIMx_ARR not preloaded)

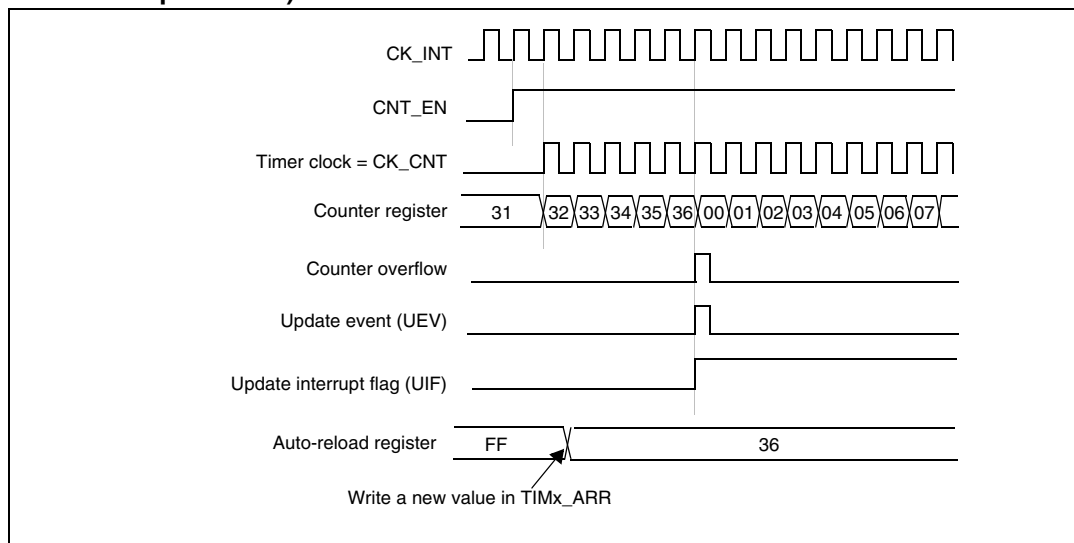
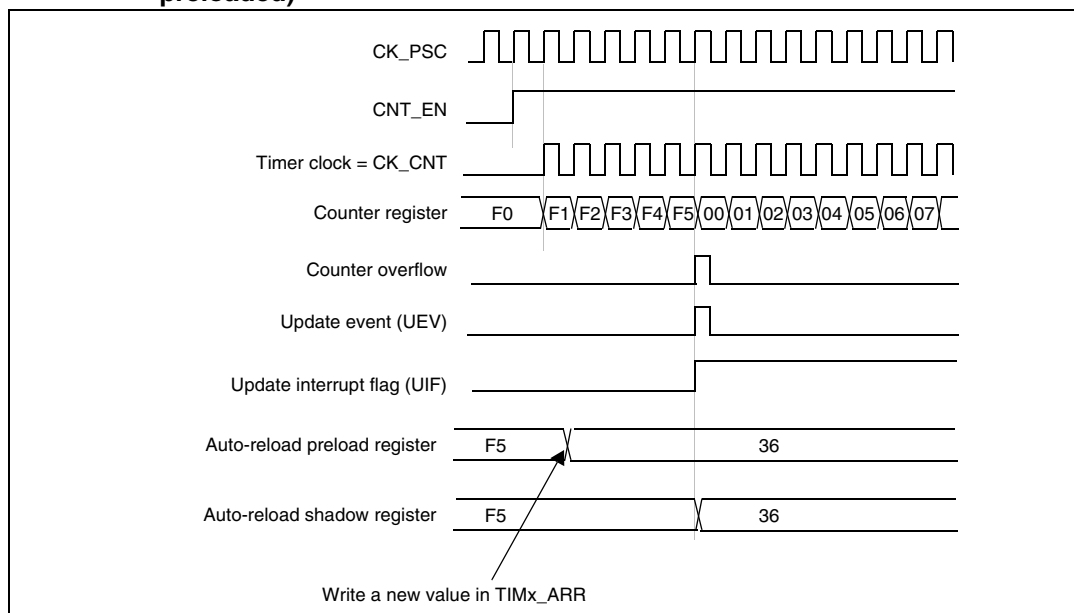


Figure 194. Counter timing diagram, update event when ARPE=1 (TIMx_ARR preloaded)

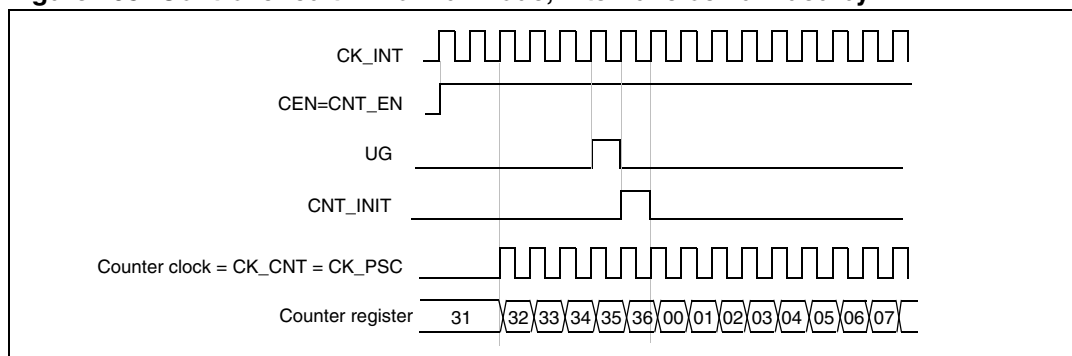


16.3.3 Clock source

The counter clock is provided by the Internal clock (CK_INT) source.

The CEN (in the TIMx_CR1 register) and UG bits (in the TIMx_EGR register) are actual control bits and can be changed only by software (except for UG that remains cleared automatically). As soon as the CEN bit is written to 1, the prescaler is clocked by the internal clock CK_INT.

Figure 195 shows the behavior of the control circuit and the upcounter in normal mode, without prescaler.

Figure 195. Control circuit in normal mode, internal clock divided by 1

16.3.4 Debug mode

When the microcontroller enters the debug mode (Cortex™-M3 core - halted), the TIMx counter either continues to work normally or stops, depending on the DBG_TIMx_STOP configuration bit in the DBG module. For more details, refer to [Section 25.15.2: Debug support for timers, watchdog and I2C](#).

16.4 TIM6&TIM7 registers

Refer to [Section 1.1 on page 32](#) for a list of abbreviations used in register descriptions.

The peripheral registers can be accessed by half-words (16-bit) or words (32-bit).

16.4.1 TIM6&TIM7 control register 1 (TIMx_CR1)

Address offset: 0x00

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
Reserved								ARPE	Reserved				OPM	URS	UDIS	CEN
								rw					rw	rw	rw	rw

Bits 15:8 Reserved, always read as 0

Bit 7 **ARPE**: Auto-reload preload enable

0: TIMx_ARR register is not buffered.

1: TIMx_ARR register is buffered.

Bits 6:4 Reserved, always read as 0

Bit 3 **OPM**: One-pulse mode

0: Counter is not stopped at update event

1: Counter stops counting at the next update event (clearing the CEN bit).

Bit 2 URS: Update request source

This bit is set and cleared by software to select the UEV event sources.

0: Any of the following events generates an update interrupt or DMA request if enabled.

These events can be:

- Counter overflow/underflow
- Setting the UG bit
- Update generation through the slave mode controller

1: Only counter overflow/underflow generates an update interrupt or DMA request if enabled.

Bit 1 UDIS: Update disable

This bit is set and cleared by software to enable/disable UEV event generation.

0: UEV enabled. The Update (UEV) event is generated by one of the following events:

- Counter overflow/underflow
- Setting the UG bit
- Update generation through the slave mode controller

Buffered registers are then loaded with their preload values.

1: UEV disabled. The Update event is not generated, shadow registers keep their value (ARR, PSC). However the counter and the prescaler are reinitialized if the UG bit is set or if a hardware reset is received from the slave mode controller.

Bit 0 CEN: Counter enable

0: Counter disabled

1: Counter enabled

Note: Gated mode can work only if the CEN bit has been previously set by software. However trigger mode can set the CEN bit automatically by hardware.

CEN is cleared automatically in one-pulse mode, when an update event occurs.

16.4.2 TIM6&TIM7 control register 2 (TIMx_CR2)

Address offset: 0x04

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserved									MMS[2:0]			Reserved			
									rw	rw	rw				

Bits 15:7 Reserved, must be kept at reset value.

Bits 6:4 **MMS**: Master mode selection

These bits are used to select the information to be sent in master mode to slave timers for synchronization (TRGO). The combination is as follows:

000: **Reset** - the UG bit from the TIMx_EGR register is used as a trigger output (TRGO). If reset is generated by the trigger input (slave mode controller configured in reset mode) then the signal on TRGO is delayed compared to the actual reset.

001: **Enable** - the Counter enable signal, CNT_EN, is used as a trigger output (TRGO). It is useful to start several timers at the same time or to control a window in which a slave timer is enabled. The Counter Enable signal is generated by a logic OR between CEN control bit and the trigger input when configured in gated mode.

When the Counter Enable signal is controlled by the trigger input, there is a delay on TRGO, except if the master/slave mode is selected (see the MSM bit description in the TIMx_SMCR register).

010: **Update** - The update event is selected as a trigger output (TRGO). For instance a master timer can then be used as a prescaler for a slave timer.

Bits 3:0 Reserved, always read as 0

16.4.3 TIM6&TIM7 DMA/Interrupt enable register (TIMx_DIER)

Address offset: 0x0C

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserved							UDE	Reserved							UIE
							rw								rw

Bit 15:9 Reserved, must be kept at reset value.

Bit 8 **UDE**: Update DMA request enable

0: Update DMA request disabled.

1: Update DMA request enabled.

Bit 7:1 Reserved, must be kept at reset value.

Bit 0 **UIE**: Update interrupt enable

0: Update interrupt disabled.

1: Update interrupt enabled.

16.4.4 TIM6&TIM7 status register (TIMx_SR)

Address offset: 0x10

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserved															UIF
															rc_w0

Bits 15:1 Reserved, must be kept at reset value.

Bit 0 **UIF**: Update interrupt flag

This bit is set by hardware on an update event. It is cleared by software.

0: No update occurred.

1: Update interrupt pending. This bit is set by hardware when the registers are updated:

–At overflow or underflow regarding the repetition counter value and if UDIS = 0 in the TIMx_CR1 register.

–When CNT is reinitialized by software using the UG bit in the TIMx_EGR register, if URS = 0 and UDIS = 0 in the TIMx_CR1 register.

16.4.5 TIM6&TIM7 event generation register (TIMx_EGR)

Address offset: 0x14

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserved															UG
															w

Bits 15:1 Reserved, must be kept at reset value.

Bit 0 **UG**: Update generation

This bit can be set by software, it is automatically cleared by hardware.

0: No action.

1: Re-initializes the timer counter and generates an update of the registers. Note that the prescaler counter is cleared too (but the prescaler ratio is not affected).

16.4.6 TIM6&TIM7 counter (TIMx_CNT)

Address offset: 0x24

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CNT[15:0]															
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Bits 15:0 **CNT[15:0]**: Counter value

16.4.7 TIM6&TIM7 prescaler (TIMx_PSC)

Address offset: 0x28

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
PSC[15:0]															
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Bits 15:0 **PSC[15:0]**: Prescaler value

The counter clock frequency CK_CNT is equal to $f_{CK_PSC} / (PSC[15:0] + 1)$.

PSC contains the value to be loaded into the active prescaler register at each update event.

16.4.8 TIM6&TIM7 auto-reload register (TIMx_ARR)

Address offset: 0x2C

Reset value: 0x0000

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ARR[15:0]															
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Bits 15:0 **ARR[15:0]**: Prescaler value

ARR is the value to be loaded into the actual auto-reload register.

Refer to [Section 16.3.1: Time-base unit on page 441](#) for more details about ARR update and behavior.

The counter is blocked while the auto-reload value is null.

16.4.9 TIM6&TIM7 register map

TIMx registers are mapped as 16-bit addressable registers as described in the table below:

Table 84. TIM6&TIM7 register map and reset values

Offset	Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0						
0x00	TIMx_CR1 Reset value	Reserved																								0	ARPE	Reserved			0	OPM	0	URS	0	UDIS	0	CEN	0
0x04	TIMx_CR2 Reset value	Reserved																								MMS[2:0]			Reserved			Reserved							
		0			0			0																															
0x08	Reserved																																						
0x0C	TIMx_DIER Reset value	Reserved																								0	UDE	Reserved										0	UIE
0x10	TIMx_SR Reset value	Reserved																											0	UIF									
0x14	TIMx_EGR Reset value	Reserved																											0	UG									
0x18	Reserved																																						
0x1C	Reserved																																						
0x20	Reserved																																						
0x24	TIMx_CNT Reset value	Reserved																CNT[15:0]																					
		0			0			0			0			0			0			0			0			0			0			0							
0x28	TIMx_PSC Reset value	Reserved																PSC[15:0]																					
		0			0			0			0			0			0			0			0			0			0			0							
0x2C	TIMx_ARR Reset value	Reserved																ARR[15:0]																					
		0			0			0			0			0			0			0			0			0			0			0							

Refer to [Table 1 on page 36](#) and [Table 2 on page 37](#) for the register boundary addresses.