

Toshiba / Topas910





Linux 2.6.26.5 – Stand alone package

1) Introduction

Linux is a fully open-source operating system which is on GPL v2 licence. This package contains a port of Linux 2.6.26.5 and a boot strap for $\underline{\text{Toshiba Topas}910}$.

The root file system can be chosen by the user. However, a pre-compiled and pre-package one, for Topas 910, is available from $\underline{\text{bplan GmbH}}$.

The package is separated into two parts:

- Low level: A small boot code, stored at the beginning of the NOR flash, initializes the CPU and the board components. Then, it loads the user application from the NOR to the main memory and executes it.
- Linux Kernel: A fully stand alone port of Linux 2.6.26.5 to the Topas 910 board. It is stored into the NOR and loaded by the low level.



2) Contains and requirements.

Files list:

• patch 2.6.26.5 topas 910. bz2: A patch to apply to the vanilla Linux kernel 2.6.26.5

linux-2.6.26.5_topas910.tar.bz2:
 A "ready to use" Linux kernel 2.6.26.5 source tree

including a valid configuration file

config_linux_2.6.26.5_topas910:
 A valid Linux kernel configuration file

lowlevel topas910.tar.bz2:
 The low-level source code

flash.bin.zip:
 A pre compiled flash image which contains the low-

level boot code and a pre compiled Linux kernel

requirements:

In order to modify and build your own kernel, you first need a working GNU ARM tool chain. We highly recommend to use at least GCC 4.2 or higher and binutils 2.18 or higher.

A fully working development system (Linux installation with a pre-installed toolchain) is available for free, from bplan GmbH.

In this document, we will often assume the tool chain is named "arm-none-eabi-".



3) Quick-setup

Burn the flash.bin image into the Topas 910 NOR flash using the JTAG recovery utility and issue a reset. Linux will start-up and try to mount an NFS root file system on 192.168.0.1:/srv/arm1.

```
Select C:\WINNT\system32\cmd.exe - jlinkprogramtopas_a910 flash.bin

D:\JLinkDemo\jlinkprogramtopas_a918 flash.bin
SEGGER J-Link Toshiba TOPAS_918 boot loader restore.
Compiled May 2 2808 17:14:53
(c) 2888 SEGGER Microcontroller GmbH & Co. KG. www.segger.com
Solutions for real time microcontroller applications

Connecting...
JTAG speed: 8808 kHz
Core Id: 8x7926831
Reading CFI info ...
Found CFI compliant flash device:
1 block region
256 sectors with 128 KB
CFI info read successfully.
Flash ID: 8x1227E
Loading data file...
Loading binary file... [flash.bin]
3145768 bytes of data loaded sucessfully.
Erasing Sectors...
Programming flash...

O.K. - Completed after 11.777 sec
```

By the way, the Linux kernel is stored compressed into the Flash. During the decompression, the Topas 910 band display will toggle. This is useful to prove that, at least, this process is in progress.

```
toshiba@ToshibaDevB5D: ~
                                                                              \square \times
Sending DHCP requests ., OK
IP-Config: Got DHCP answer from 192.168.1.1, my address is 192.168.0.3
IP-Config: Gateway not on directly connected network.
Looking up port of RPC 100003/2 on 192.168.0.1
Looking up port of RPC 100005/1 on 192.168.0.1
VFS: Mounted root (nfs filesystem) readonly.
Freeing init memory: 120K
mount: mounting configfs on /config failed: No such device
Starting portmap: done
Initializing random number generator... read-only file system detected...done
Starting network...
ip: RTNETLINK answers: File exists
Starting telnetd: done
Starting Dropbear SSH server: dropbear.
Welcome to bplan GmbH tiny Linux.
 contact: opensource@bplan-gmbh.de
inux login:
```



4) The lowlevel

This is a small boot code which initialises the board components, loads an application from the NOR flash to memory and executes it.

You can change the application offset and size into the file "startmeup.S". Example with the default values:

```
#define APP_RAMLOCATION 0x41000000

#define APP_NORLOCATION 0x20040000

#define APP_SIZE 0x00200000

NOR [0x20040000 - 0x00240000] -> Copy -> RAM 0x41000000

#define APP2_RAMLOCATION 0x43000000

#define APP2_NORLOCATION 0x20600000

#define APP2_SIZE 0x00300000

NOR [0x20600000 - 0x20900000] -> Copy -> RAM 0x43000000
```

Once, the whole user application has been loaded, the boot code jumps to the first RAM location: $APP_RAMLOCATION$. In this case, a Linux kernel is copied at 0x41000000 and a Linux RAM Disk at 0x43000000. Then, the code jumps to 0x41000000 and Linux starts up.

The default toolchain is "arm-none-eabi-". If you have another one installed, edit the Makefile and change the toolchain option:



Once your are done with your modification, type "make" to build the lowlevel. It will generate a file named "bootstart tmpa910.bin" which has to be burn at offset 0x0 into the NOR Flash.

```
Assembling build/low_dm9000.o... Done
Assembling build/low_smc.o... Done
Assembling build/low_dmc.o... Done
Assembling build/low_clocks.o... Done
Assembling build/low_lcd.o... Done
Assembling build/low_misc.o... Done
Assembling build/low_misc.o... Done
Assembling build/minicon_common o... Done
Assembling build/minicon.o... Done
Compiling build/low_sdhc.o... Done
Compiling build/low_sdhc.o... Done
Final Linking bootstart_tmpa910.prebin.elf.db... Done
Striping bootstart_tmpa910.prebin.elf... Done
Extracting bin bootstart_tmpa910.bin... Done
toshiba@ToshibaDevBSD:~/src/linux/lowlevel$
```



5) First build and boot option

Build:

First, uncompress the tarball (linux-2.6.26.5_topas910.tar.bz2) somewhere. There is two options to give to the make command to build a valid ARM kernel:

- ARCH=arm: Force to compile for ARM. Otherwise, the build will be done for your own system.
- CROSS_COMPILE=arm-none-eabi-: Specify the tool chain to use. Here "arm-none-eabi-" is an example. You have to adapt it to your environment.

A valid command is:

```
> make ARCH=arm CROSS_COMPILE=arm-none-eabi-
```

After a while, the kernel is built. The file "arch/arm/boot/zImage" contains the compressed kernel and a small header to expand it. This file can be loaded into the TMPA910 memory and executed directly.

```
toshiba@ToshibaDevB5D: ~/src/linux/linux-2.6.26.5_topas
 SYSMAP
         .tmp_System.map
 OBJCOPY arch/arm/boot/Image
 Kernel: arch/arm/boot/Image is ready
 AS
         arch/arm/boot/compressed/head.o
 GZIP
         arch/arm/boot/compressed/piggy.gz
 AS
         arch/arm/boot/compressed/piggy.o
 CC
         arch/arm/boot/compressed/misc.o
         arch/arm/boot/compressed/vmlinux
 LD
 OBJCOPY arch/arm/boot/zImage
 Kernel: arch/arm/boot/zImage is ready
 Building modules, stage 2.
 MODPOST 1 modules
         drivers/scsi/scsi_wait_scan.mod.o
 LD [M] drivers/scsi/scsi_wait_scan.ko
toshiba@ToshibaDevB5D:~/src/linux/linux-2.6.26.5_topas$
```



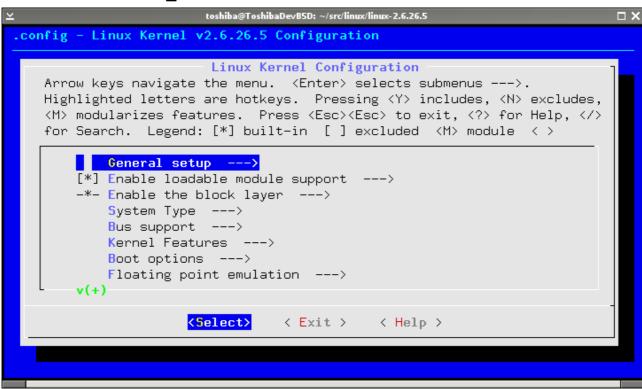
Kernel configuration:

A valid configuration is delivered with the Linux tarball. However, you will likely want to adapt the kernel options to your exact needs.

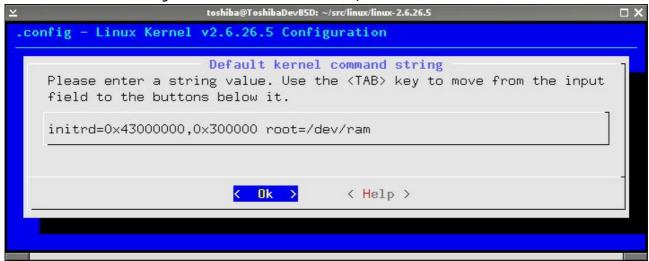
As an example, if you do not need the touch screen controller driver, you could disable the Linux input device system.

To change the Linux configuration enter the following command:

> make ARCH=arm CROSS COMPILE=arm-none-eabi- menuconfig



You will likely want to change your boot option. For example, to use a RAM Disk image, located at 0x43000000 as root file system enter the following parameter into "Boot options -> Default kernel command string": "initrd=0x43000000, 0x300000 root=dev/ram"





6) Device support

Interrupt controller: Provides interrupt to the Linux kernel

• Timer controller: The TMPA910 Timer 0 is used as time base for the Kernel

Serial controller: Provides serial communication. This can be use for a serial

console or to control external peripherals

Davicom DM9000: Provides Ethernet network connection. It pops up as

"eth0" into Linux.

• LCD Controller: Provides a 320x240 24bits frame buffer on the on-board

display. This device is located at /dev/fb0, into the Linux

file system

• Touch Screen: Provides user interaction. It is implemented as an Linux

input device. It is at /dev/input/event0. We recommend

to use the tslib to take full advantage of this device



7) FAQ

• I booted my system with the root file system provided on the bplan development environment. Telnet and SSH are working but I get no serial console login. Why?

This root file system is configured to use the aura/hvc console. However, the standalone Linux use the serial port located at "/dev/ttyS0". You have to edit the file "/etc/inittab" and replace "hvc0" by "ttyS0".

• Linux reports only 63 MB of memory. However, there are 64 MB mounted on the board. Why is 1 MB missing?

We reserved the last mega bytes of memory [0x43f00000 - 0x4400000] for the frame buffer.

If you are not using the display and which to have access to the full RAM, disable the TMPA910 Frame buffer driver and edit

"include/asm/arm/arch/tmpa910/memory.h".



8) Links and resources

 Official Linux kernel: http://www.kernel.org

Toshiba TMPA910:
 http://www.toshiba-components.com/microcontroller/TMPA910.html

 GNU development and toolchain: http://gcc.gnu.org/

 http://www.gnu.org/software/binutils/

 Official ARM info center: http://infocenter.arm.com/



9) Contact

This software has been developed and is copyright bplan GmbH.

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10) Licence

The Linux kernel is under GPLv2 licence:

http://www.gnu.org/licenses/gpl-2.0.html

The low level boot code is under BSD Licence:

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