
AVR32005: AVR32 AP7 How to add a custom board to Buildroot

Features

- Adding a custom board to the Buildroot configuration system
- Creating a default Buildroot board configuration

1 Introduction

This application note describes how a custom target board can be added to the Buildroot build system. A custom board is useful if you intend to use Buildroot in combination with your own design.

The custom board can contain board specific kernel patches and the Buildroot configuration file for this board can enable a default selection of packages. This eases the recreation of the root file system for a custom board.



32-bit **AVR**[®]
Microcontrollers

Application Note

Rev. 32085B-AVR-11/08





2 Creating a custom board

In this application note the *atngw100-base* board is used as an example to implement a custom board. This approach has the advantage that it can be used as a template and it only contains, as the name implies, a basic setup for the NGW100 board.

All files needed are located in the directory *target/device/Atmel/atngw100-base*. To start a new board create a new directory in *target/device/Atmel* and name it after your board. After that copy all files and directories in *atngw100-base/* to this directory.

These files and directories are discussed in the next chapters.

2.1 Linux® configuration

The kernel needs a valid configuration for your board. This configuration is stored in the kernel sources in the *.config* file. The file *linux-2.6.25.10.config* in your new board directory is such a configuration file. It will be copied to the kernel sources when you initiate a build for your board. The version may vary according to the last kernel release. Rename the file to fit your kernel version.

- Change *2.6.25.10* to your kernel version

If you do not want to use this configuration, configure the kernel and copy the *.config* file to your board directory. Rename it as described earlier. To run the kernel configuration within Buildroot run:

```
make linux26-menuconfig
```

You also have the possibility to use a default kernel configuration shipped with the kernel source. To use this you have to change the Buildroot configuration:

```
Kernel --->
  Kernel type (linux (Advanced configuration)) --->
    Linux Kernel Configuration --->
      Linux Kernel Configuration (Run make <custom>_defconfig) --->
        (yourboard_defconfig) make custom_defconfig
```

The kernel sources are loaded from the official website (<http://ftp.kernel.org>). The official release may not include all AVR®32 specific changes and might need a patch. In addition the board setup code for the Linux kernel, which is specific for each board, may be included in this patch.

All kernel patches must reside in the *kernel-patches/* directory under your board directory in order to let Buildroot automatically apply them. The patches are applied in an alphabetical order. So if you need to follow a specific sequence, name the patches appropriately.

2.2 Busybox configuration

Busybox is a set of common Linux tools such as *ls*, *cat* and *echo*, which are combined into one binary to reduce size. More information is available on <http://www.busybox.net>.

To select the tools that you want on your target system, a configuration file is needed. The file *busybox.config* in your board directory is such a configuration for Busybox. Edit this file to add/remove tools from Busybox.

To run the Busybox configuration within Buildroot run:

```
make busybox-menuconfig
```

This command will overwrite the Busybox board configuration in the board target directory.

NOTE: exit with *Ctrl + c* will not copy the config file.

2.3 Target file system

Your target board needs a root file system. A skeleton for the root file system is available in the directory *target_skeleton/* in your board directory. Here you can add new directories and files. The files and directories here will be copied to the root file system. File attributes such as the group id (gid) or permissions you set here will be ignored.

In order to set file attributes and to create special files the file *device_table.txt* exists. Here you can modify the attributes of existing files and directories or add new ones. It is also possible to create special files like device files or fifo's.

The reason of having a *device_table.txt* file is that you can build the whole target root file system as normal user and thus do not have to switch to root. A short documentation about editing the *device_table.txt* file is included in the same file.

2.4 Board Makefile

In the file *Makefile.in* change the path to your board directory, remove *ATNGW100_BASE* from *BR2_TARGET_AVR32_ATNGW100_BASE* and replace it with your board name. Do the same with *ATNGW100_BASE_PATH*. Unless you did not change the name/directory of *target_skeleton* and *device_table.txt* no further changes are needed here.

```
ifeq ($(BR2_TARGET_AVR32_ATNGW100_BASE),y)
ATNGW100_BASE_PATH=target/device/Atmel/atngw100-base
TARGET_SKELETON=$(ATNGW100_BASE_PATH)/target_skeleton
TARGET_DEVICE_TABLE=$(ATNGW100_BASE_PATH)/device_table.txt
endif
```

3 Adding a board to the configuration system

In order to make a new board visible and selectable in the Buildroot configuration system it must be added as an entry in a configuration file. The file of interest is *target/device/Atmel/AVR32_Config.in*. In this file an entry is needed to make your board selectable from the menu.

Open the file *AVR32_Config.in* and copy the entry for the NGW100 base board to make a new insertion right after it. Make sure that the entry is between the labels *choice* and *endchoice*.

```
config BR2_TARGET_AVR32_ATNGW100_BASE
    bool "Atmel AVR32 basic network gateway board support"
    depends BR2_at32ap7000
```





```
select BR2_PACKAGE_LINUX
```

```
help
```

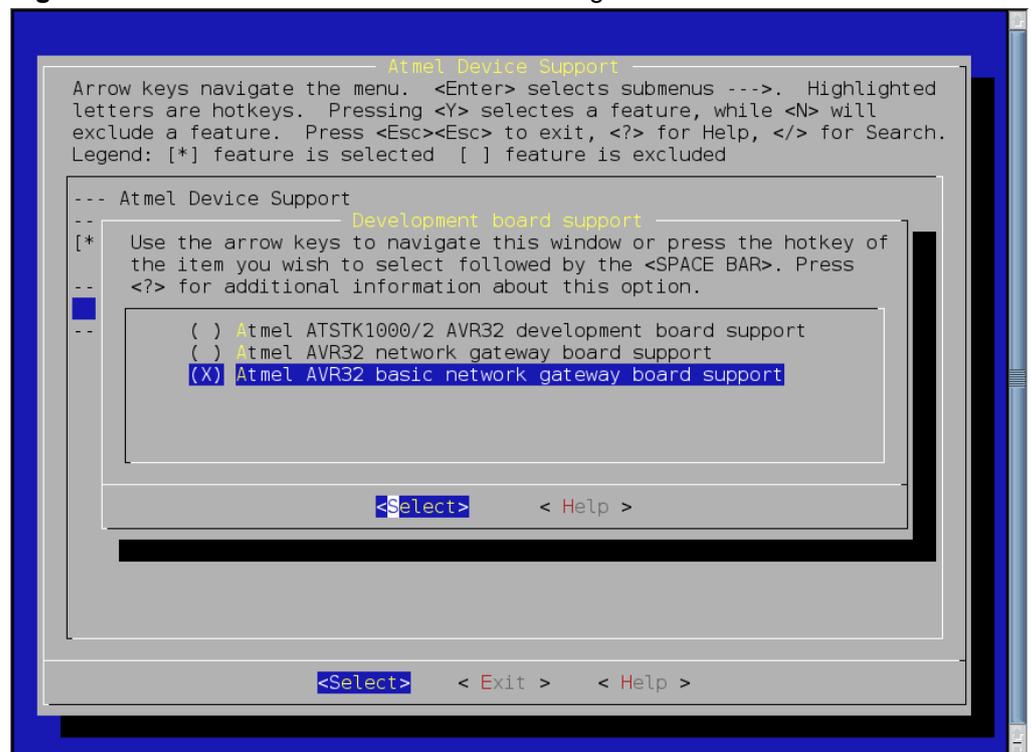
Very simple configuration for the Atmel AVR32 Network Gateway Board.

Now edit the entry:

- Replace `BR2_TARGET_AVR32_ATNGW100_BASE` with your Buildroot board name (something like `BR2_TARGET_AVR32_YOUR_BOARD_NAME`; make sure it is the same name as in chapter 2.4).
- Add a description for the menu entry after `bool`.
- Depending on the device that is mounted onto your custom board, add the correct target device after `depends`. Supported devices are listed in the same file as configuration options.
- It is mandatory to enable the Linux package with “select `BR2_PACKAGE_LINUX`”.
- Add a detailed board description after the `help` attribute if you like. This description appears in the menu system as help message.

The board is now available in the menu under “Board Support Options -> Atmel Device Support -> Development board support”. It will be shown in the development board support list as shown in Figure 3-1.

Figure 3-1. Board selection in the Buildroot configuration



Last step is to edit the file `target/device/Atmel/Config.in`. The `BR2_BOARD_NAME` configuration parameter needs the correct board name. The name has to be the directory in `target/device/Atmel` in which the custom board files are located.

```
config BR2_BOARD_NAME
    string
    ...
    default "atngw100-base" if BR2_TARGET_AVR32_ATNGW100_BASE
```

The example above reflects only the relevant part of the `BR2_BOARD_NAME` configuration in the `Config.in` file. Other boards are replaced by "...". Copy the last line and add it right after it. Replace "atngw100-base" with your board directory and `BR2_TARGET_AVR32_ATNGW100_BASE` with your Buildroot board configuration.

After these steps your custom board is integrated in the Buildroot build system. The only thing left to do is to enable your board in the configuration.

4 Creating a Buildroot configuration

When you build an image for a board you typically run `make atngw100_defconfig` or a similar command depending on the board. Refer to the application note *AVR32003 Buildroot for AVR32* for more information. This command copies the specified configuration file to the file `.config` and runs a check to see if the configuration is sane. After that you can make additional selections by running `make menuconfig`. To benefit of this feature for your board you have to create a board default configuration file.

Run `make atngw100-base_defconfig` to get a basic configuration loaded from which you can start to make your own. Other configurations are also possible but they will, most likely, have many things configured that you probably will not need. Now run `make menuconfig` to alter the settings. To activate your board go to the menu entry described in chapter 3.

Select packages and edit all options to your needs. When you are finished leave the configuration system and save your settings. Copy the `.config` file to the directory `target/device/Atmel/<your board name>` and name it after your board with a `_defconfig` extension at the end of the file name. Now it is possible to run `make your_board_name_defconfig` and Buildroot loads your default settings.





Headquarters

Atmel Corporation
2325 Orchard Parkway
San Jose, CA 95131
USA
Tel: 1(408) 441-0311
Fax: 1(408) 487-2600

International

Atmel Asia
Unit 1-5 & 16, 19/F
BEA Tower, Millennium City 5
418 Kwun Tong Road
Kwun Tong, Kowloon
Hong Kong
Tel: (852) 2245-6100
Fax: (852) 2722-1369

Atmel Europe
Le Krebs
8, Rue Jean-Pierre Timbaud
BP 309
78054 Saint-Quentin-en-
Yvelines Cedex
France
Tel: (33) 1-30-60-70-00
Fax: (33) 1-30-60-71-11

Atmel Japan
9F, Tonetsu Shinkawa Bldg.
1-24-8 Shinkawa
Chuo-ku, Tokyo 104-0033
Japan
Tel: (81) 3-3523-3551
Fax: (81) 3-3523-7581

Product Contact

Web Site
www.atmel.com

Technical Support
avr@atmel.com

Sales Contact
www.atmel.com/contacts

Literature Request
www.atmel.com/literature

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. **EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDITIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.** Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

© 2008 Atmel Corporation. All rights reserved. Atmel®, logo and combinations thereof, AVR® and others, are the registered trademarks or trademarks of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.